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Resonant Radiation of Boundary with a Travelling Distribution of the Field

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ABSTRACT: The problem of acoustic monochromatic radiation by boundary with a traveling distribution of phases of normal vibrational velocities is considered. It is shown that when the spatial frequency of the traveling phase of normal velocities approaches the wave number in the medium, the energy transfer from boundary into a "sliding" (with respect to the boundary) sound wave can resonantly increase to a value many times greater than the energy transfer from of the in-phase boundary, correspondingly, into the normal one (with respect to the boundary) sound wave at the same modules of amplitudes of vibrational velocities of boundary. In addition, the resonant energy transfer of the boundary into a "sliding" wave is the greater, the larger the wave dimensions of the radiating pattern on boundary. It is shown that when a similar traveling distribution of sound pressure (instead normal velocity) is specified at the boundary, there is no resonance. The influence of the curvature of the radiating boundary on the above phenomenon of resonant radiation was studied. It is shown that the resonant radiation of the boundary with given running phases of normal velocities generates a tangential (with respect to the boundary) constant in time radiation reaction force. It is shown that for the case of a linear chain of equidistant monopoles (or pulsing spheres separated from each other by medium) with a traveling phase (a traveling wave antenna) of their oscillatory velocities, the resonance does not appear.

KEYWORDS: Boundary, Pattern, radiation, Resonance, Phasor, Spatial frequency, Radiation pressure

1. Introduction

It is usually well-known that there is radiation (acoustical or electromagnetic monochromatic field in the far zone) at the spatial frequency $h_0 < k_0$ (k_0 -wave number in the medium) of sources, and at the spatial frequency $h_0 > k_0$ of sources radiation is absent or very small [1-7]. This is probably why the researchers did not consider this area in sufficient detail. Below, using several examples of very simple boundary value problems [8], it is shown that radiation power with an increase in the spatial frequency h_0 from $h_0 = 0$ to $h_0 > k_0$ (immediately before radiation falling to zero at $h_0 > k_0$) can reach infinity when approaching h_0 to k_0 . This means the phenomenon of resonance, which is of particular interest to any physicist, especially since we are talking about such an important physical quantity as the surface density of the radiated power. On the other hand, it is known that the traveling amplitude distribution of radiating elements (separated from each other by the medium) in traveling wave antennas does not lead to resonant radiation [9]. In addition, many highly educated researchers, without delving into details (on the basis of the hastily applied relationship between pressure and velocity through the impedance of the medium), are inclined to declare that there is no fundamental difference between boundary radiation with a given pressure and boundary radiation with a given normal velocity. Thus the purpose of this work is to fill the above-mentioned small, but very common (as experience shows) gaps in understanding the process of wave radiation.

First, let's consider a sound field excited in a compressible nonviscous linear medium (in a half-space $z \ge 0$) by a traveling distribution (with a traveling phase [8])

$$U_0(\mathbf{r},t) = U(h_0,\omega_0)\exp(i\omega_0 t - ih_0 x)$$
(1)



of normal vibrational velocities on the surface S (plane surface S, z = 0, $\mathbf{r} = (x, y, 0)$), where $U(\omega_0, h_0)$ is the complex amplitude of travelling wave on the time frequency ω_0 and spatial frequency h_0 of normal vibrational velocities (Fig. 1-a). Below we will consider the radiation of various patterns (as modifications of (1)) with a traveling phase.

2. Plane (acoustical field)

Particle velocity $\mathbf{v}(x, z, t)$ and sound pressure p(x, z, t) are determined by potential ψ as

$$\mathbf{v}(\mathbf{r},t) = -\operatorname{grad}(\psi), \ p(\mathbf{r},t) = \rho \psi_t^{\prime}, \qquad (2)$$

where ρ is the mass density of medium at z > 0.



Figure 1. Radiation of the boundary: (a) acoustical radiation; (b) electromagnetic radiation.

Assuming the spatial two-dimensionality of the boundary value problem (i.e. $\partial / \partial y = 0$, $-\infty < y < +\infty$), let us substitute the solution in the equation

$$\psi_{xx}^{\prime\prime} + \psi_{zz}^{\prime\prime} = c^{-2} \psi_{tt}^{\prime\prime}$$
(3)

(*c* is the speed of sound in a compressible medium) for the acoustic wave potential $\psi(x, z, t)$ in the form

$$\psi(x, z, t) = X(x)Z(z)T(t)$$
(4)

with functions X(x), Z(z), T(t) of separable variables x, z, t in the absence of waves incident on the boundary z = 0. In this case for wave potential $\psi(x, z, t)$ (in the absence of incident waves and satisfying the boundary condition (1) or $-\psi(x, z, t)_z^{\prime} = U_0(x, t)$) we obtain the following expression

$$\psi(x, z, t) = \varphi(x, z, t) + \overline{\varphi}(x, z, t), \qquad (5)$$

where

(

$$p(x, z, t) = \frac{\exp\left(-iz\sqrt{k_0^2 - h_0^2}\right)}{\left(-i\sqrt{k_0^2 - h_0^2}\right)} \mathbf{I}[k_0 - |h_0|]e^{i\omega_0 t - ih_0 x} U(h_0, \omega_0),$$
(6)

$$\overline{\varphi}(x,z,t) = \frac{\exp\left(-z\sqrt{h_0^2 - k_0^2}\right)}{\left(-\sqrt{h_0^2 - k_0^2}\right)} \mathbf{I}[|h_0| - k_0] e^{i\omega_0 t - ih_0 x} U(h_0,\omega_0), (7)$$

 $\mathbf{I}[\boldsymbol{\xi}]$ -Heaviside step function ($\mathbf{I}[\boldsymbol{\xi} < 0] = 0$, $\mathbf{I}[\boldsymbol{\xi} \ge 0] = 1$), (8)

thus $\psi = \varphi$ at $|h_0| < k_0$, $\psi = \overline{\varphi}$ at $|h_0| > k_0$, where $k_0 = \omega_0 / c$. Now we get the power flux density

$$W(h_0) = \operatorname{Re}[\rho(\psi_t^{\prime})(\psi_z^{\prime})^*]_{z=0} / 2$$
(9)

or
$$W(h_0) = (\omega_0 \rho / 2) |U(h_0, \omega_0)|^2 \mathbf{I}[k_0 - |h_0|] / \sqrt{k_0^2 - h_0^2}$$

(10)

at the boundary z = 0. This is the work performed by a section of a strip of unit width (along the axis "*x*") and unit length (along the axis *y*) and averaged in time over a period $2\pi / \omega_0$). This is due to an abrupt change in the eigenvalue of the boundary value problem from purely real to purely imaginary when going from $|h_0| < k_0$ to $|h_0| > k_0$. For the reactive power flow, we obtain the expression

$$\overline{W}(h_0) = \operatorname{Im}[\rho(\psi_t^{\prime})(\psi_z^{\prime})^*]_{z=0} / 2$$
(11)

or
$$\overline{W}(h_0) = \omega_0 \rho |U(h_0, k_0)|^2 \mathbf{I}[|h_0| - k_0] / (2\sqrt{h_0^2 - k_0^2}).$$
(12)

Normalizing to the value W(0) (i.e. for $h_0 = 0$, or in a onedimensional radiation problem), we obtain a simple expression that means the resonant dependence for relative active $W(h_0)$ and reactive $\overline{W}(h_0)$ power flux density (Fig. 2-a, 2-b)

$$\left[W(h_0) / W(0) \right]_1 = \mathbf{I} [k_0 - |h_0|] / \sqrt{1 - (h_0 / k_0)^2}$$
 (Fig. 2-a),
(13) $\left[\overline{W}(h_0) / W(0) \right]_1 = \mathbf{I} [|h_0| - k_0] / \sqrt{(h_0 / k_0)^2 - 1}$ (Fig. 2-a),
(14)

of the energy transfer of the boundary z = 0 (into the halfspace $z \ge 0$). Lines **P** (Pointing vector) of power flow go out of the plane z = 0 at an angle of inclination

$$\alpha = \arccos(h_0 / k_0) . \tag{15}$$

However, when the traveling pressure

$$\rho \psi_t^{\prime}(x,t) \sim \exp(i\omega_0 t - ih_0 x) \tag{16}$$

is set at the boundary z = 0, there is no resonance in the following corresponding functions (instead (13), (14))

$$\left[W(h_0) / W(0)\right]_{p1} = \sqrt{1 - (h_0 / k_0)^2} \mathbf{I}[k_0 - |h_0|] \text{ (Fig. 2-c) (17)}$$



$$\left[\overline{W}(h_0) / W(0)\right]_{p1} = \sqrt{(h_0 / k_0)^2 - 1} \mathbf{I}[|h_0| - k_0] \text{ (Fig. 2-d),}$$
(18)

(contrary to superficial judgment about the relationship between pressure and velocity through the impedance of the medium, see Figs. 2-c, 2-d).



Figure 2. Resonant radiation of the infinite plane boundary **S** with: (a) normalized real power (13) for velocity pattern (1); (b) normalized imaginary power (14) for velocity pattern (1); (c) normalized real power (17) for given pressure pattern (16); (d) normalized imaginary power (18) for given pressure pattern (16), left white area corresponds to real

part of power (radiation), right gray area means reactive imaginary power (no radiation); (e) radiation of normal wave by pattern with amplitude modulus Δ , phasor $h_0 = 0$, $\alpha = \pi / 2$; (f) radiation of a "sliding" wave ($\alpha \ll 1$) with the same amplitude modulus Δ of the pattern, and with a phasor $h_0 \rightarrow k_0$.

Below, the value $\left[W(h_0)/W(0)\right]_n$ (n = 1-5, i.e. in various modifications) will also be called the transmission function (in terms of power) of a spatial low-frequency filter (due to boundary value problem, Fig. 1) of spatial frequencies h_0 or also the normalized (by W(0)) radiation resistance of a radiating pattern (pattern number n = 1-5) with spatial frequency h_0 along the vector called as phasor \mathbf{h}_0 . Below the quantity $U_0(x,t)$ we also will call "pattern" with surface or boundary S.

The essence of the effect of resonant radiation: the wave generated by the pattern (1) at $|k_0 - |h_0|| / k_0 \ll 1$, takes much more energy for radiation (from the devices that support the pattern (1)) than the wave with $h_0 = 0$ (at the same fixed amplitude module $\Delta = |U(h_0, \omega_0)|$ of pattern (1), Fig. 2-e, 2-f). In turn, devices that support pattern (1) must have an infinite internal impedance $Z_U = \infty$ (or not depend on any wave pressure at z > 0) or an impedance $Z_U \gg \rho c$ that is many times greater than the impedance ρc of the medium (at $z \ge 0$), for example: air (z > 0)—piezoceramic (thickness ℓ , $0 > z > -\ell$)—steel ($z < -\ell$).

Here is another explanation of the effect. When $|k_0 - h_0|| / k_0 < 1$, the solution of equation (3) in the halfspace z > 0 is a plane sound wave with a wave potential $\psi(x, z, t) = A \exp(i\omega t - ik_0 x \cos \alpha - ik_0 z \sin \alpha)$, where *A* is the magnitude. To fulfill condition (1) at the boundary z = 0, the amplitude *A* of the radiated wave must be increased at $|h_0| \rightarrow k_0$ (or $\alpha \rightarrow 0$) so that the projection $-[\psi_A(x, z, t)]_z'$ of particle velocities in the radiated wave ψ onto the axis "*z*" coincides with pattern (1), which magnitude has been given independently on α . But supporting a given pattern (1) at $\alpha \rightarrow 0$ requires more and more energy (energy of radiation).

3. Plane (electromagnetic waves).

The resonance characteristics (13), (14) described above are a property of the wave equation. Therefore, it is natural to assume the possibility of their appearance in the boundary value problem for an electromagnetic field. And indeed, for instance, the tangential electric field

$$\mathbf{E}_0 \sim \mathbf{h}_0 \exp[i\omega_0 t - ih_0 x] \tag{19}$$

 $(\mathbf{E}_0 \parallel (z=0), \mathbf{h}_0 \parallel (z=0))$ on the plane S or z = 0 (see Fig. 1b) determines the electromagnetic field in the entire halfspace $z \ge 0$. When specifying a tangential electric field \mathbf{E}_0 on the plane z = 0 (we emphasize, not an electric current or a source on the right side of the boundary conditions, namely the field \mathbf{E}_0), we get the same resonance functions (13), (14) $[W(h_0)/W(0)]_1$ and $[\overline{W}(h_0)/W(0)]_1$.

4. Plane (acoustical radiation pressure). Let us return to the acoustic problem as in Section 2. The pattern $U_0(x,t)$ creates a nonzero complex amplitude of sine $\sin[\phi(x,t)]$ ($\phi(x,t)$ is the slope of the border z = 0 or a normal $\mathbf{n}(x,t)$, Fig. 3, $|\phi| \ll 1$ at $|\phi| \ll 1$) is equal to the following expression

$$(h_0 / \omega_0) U(h_0, \omega_0) \exp(i\omega_0 t - ih_0 x)$$
. (20)

Due to this, the local pressure force of the medium on the boundary z = 0 at the point x at t the moment has a tangential component

$$\mathbf{F}(x,t) = -(\mathbf{h}_0 / |\mathbf{h}_0|) p(x,0,t) \sin(\phi(x,t)).$$
(21)

The average (for the time period $2\pi / \omega_0$ and for the spatial period $2\pi / h_0$) value of the force **F** (force per unit square of surface **S**, z = 0) is equal to



$$\langle \mathbf{F} \rangle_{x, t} = -(\mathbf{h}_0 / |\mathbf{h}_0|) \operatorname{Re}[p(x, 0, t) * \sin(\phi(x, t))] / 2$$
 (22)

or
$$\langle \mathbf{F} \rangle_{x, t} = -(\mathbf{h}_0 / |\mathbf{h}_0|) c_U^{-1} W(h_0)$$
, (23)

where $c_{\rm U} = \omega_0 / h_0$ is the phase velocity of the pattern $U_0(x,t)$ (or the speed with which it would be necessary to translate the rigid profile

$$\eta(x) = -[U(h_0, \omega_0) / h_0 c_{\rm U}] \cos(h_0 x)$$
(24)

along the axis "x" (i.e. $\eta(x) \rightarrow \eta(x - c_U t)$, see (1)) in order to obtain the distribution $U_0(x,t)$ of normal velocities), $W(h_0)$ is the radiation power density of the boundary z = 0.



Figure 3. On the appearance of tangential acoustical radiation pressure on an infinite flat pattern.

Obviously: (a) $\langle \mathbf{F} \rangle_{x, t} \neq 0$ is quadratic effect for $U_0(x, t)$; (b) $\langle \mathbf{F} \rangle_{x, t} = 0$ at $W(h_0) = 0$ (i.e. at $|h_0| > k_0$). On the other hand, the pattern acts on the liquid with a force $\overline{\mathbf{F}} = -\mathbf{F}$ (or $\langle \overline{\mathbf{F}} \rangle_{x, t} = -\langle \mathbf{F} \rangle_{x, t}$) that can generate a flow in liquid. Thus, we have obtained the radiation reaction force for a perfectly linear compressible nonviscous medium (unlike [10]). Now consider the case when the pattern (1) of normal vibrational velocities (at the boundary z = 0)

$$U_0(x,t) = \sum_{h_{0n} > 0} u_{0n} e^{i\omega_0 t - ih_{0n}x} + \sum_{h_{0n} < 0} u_{0n} e^{i\omega_0 t - ih_{0n}x}$$
(25)

represented by a set of sinusoids at spatial frequencies $\{h_{0n}\}$ and with amplitudes u_{0n} (n = 1,2,3,...). Some of these sinusoids run to the left ($h_{0n} < 0$), some of the sinusoids run to the right ($h_{0n} > 0$). Accordingly, the projection ($\langle \mathbf{F} \rangle_{x,t}$)_x of the tangential force $\langle \mathbf{F} \rangle_{x,t}$ (per unit area of the plane z = 0) of the radiation reaction on the axis "x" is presented by term ($\langle \mathbf{F} \rangle_{-}$)_x (caused by spatial harmonics running to the left, i.e. $h_{0n} < 0$, n = 1,2,3,...) and term $-(\langle \mathbf{F} \rangle_{+})_x$ (caused by spatial harmonics running to the right, i.e. $h_{0n} > 0$, n = 1,2,3,...):

$$(\langle \mathbf{F} \rangle_{x,t})_{x} = (\langle \mathbf{F}_{-} \rangle_{x,t})_{x} - (\langle \mathbf{F}_{+} \rangle_{x,t})_{x},$$
 (26)

where, using (10) and (23), we can write

$$(\langle \mathbf{F}_{-} \rangle_{x,t})_{x} = \sum_{h_{0n} > 0} \left| u_{0n} \right|^{2} c_{\mathrm{Un}}^{-1} \omega_{0} \rho (k_{0}^{2} - h_{0n}^{2})^{-1/2} \mathbf{I} (k_{0} - \left| h_{0n} \right|),$$
(27)

$$(\langle \mathbf{F}_{+} \rangle_{x,t})_{x} = \sum_{h_{0n} < 0} \left| u_{0n} \right|^{2} c_{\mathrm{Un}}^{-1} \omega_{0} \rho (k_{0}^{2} - h_{0n}^{2})^{-1/2} \mathbf{I} (k_{0} - \left| h_{0n} \right|),$$
(28)

where $\mathbf{I}[\xi]$ -Heaviside step function (see (8)), $c_{\text{Un}} = \omega_0 / |h_{0n}|$. From (26)-(28) it is easy to see that the value (26) is the balance of the power of waves radiated to the right ($h_{0n} > 0$) and the power of waves radiated to the left ($h_{0n} < 0$).

5. Cylinder (azimuthal phasor)

Next, we will continue to consider examples of resonant radiation by various patterns. Let's consider patterns with a finite curvature of a bearing surface - an infinite cylindrical surface S of pattern with a cross-sectional radius R, on which a certain distribution $U_0(\mathbf{r}, t)$ of normal vibrational velocities is given (Fig. 4-a).



Figure 4. The phase runs along the azimuth \mathscr{G} of the cylinder S: (a) geometry of the boundary value problem; (b) normalized radiation resistance $\left[W(h_0)/W(0)\right]_2$ at different wave sizes k_0R of the cylinder cross-section, (the gray line shows the function

 $\left[W(h_0) \, / \, W(0)\right]_1$); (c) dependence of the peak value M_2 on $k_0 R$.

Using the cylindrical wave equation (instead (3))

$$r^{-1} \left(r \psi_r^{\prime} \right)_r^{\prime} + r^{-2} \psi_{gg}^{\prime \prime} = c^{-2} \psi_{tt}^{\prime \prime} , \qquad (29)$$



(where r, ϑ are the corresponding cylindrical coordinates of point **r**) for pattern

$$-\left(\psi_r^{\prime}\right)_{\kappa=K} = U_0(\mathbf{r},t) = \exp(i\omega_0 t - ih_0 R \mathcal{S})$$
(30)

(the phase runs in the azimuthal direction \mathcal{B} , $0 \le \mathcal{B} < 2\pi$, $-\infty < x < +\infty$, $\partial / \partial x = 0$) we obtain the normalized radiation resistance (Fig. 4-b)

$$\left[\frac{W(h_0)}{W(0)}\right]_2 = \frac{\operatorname{Re}\left[i\left(\operatorname{H}_n^{(2)}(\xi)\right)/\left(\operatorname{H}_n^{(2)}(\xi)\right)_{\xi}'\right]_{\xi=k_0R}}{\operatorname{Re}\left[i\left(\operatorname{H}_0^{(2)}(\xi)\right)/\left(\operatorname{H}_0^{(2)}(\xi)\right)_{\xi}'\right]_{\xi=k_0R}}$$
(31)

of such a pattern, where, of course, only discrete points $h_0 = n/R$ have a mathematical (and physical) meaning $(H_n^{(2)}(\xi)$ is the Hankel function of the second kind of the n-th order, n = 0,1,2,...). Looking at the evolution of the graphs of the magnitude $[W(h_0)/W(0)]_2$ with increasing k_0R , one could assume that

$$\lim_{k_0 R \to \infty} \left[W(h_0) / W(0) \right]_2 = \frac{1}{2} \left[W(h_0) / W(0) \right]_1.$$
(32)

However, the convergence of these values significantly slows down (this can be judged by the slowdown in the growth of the maximums (varying h_0)

$$M_{2}(k_{0}R) = \max_{h_{0}} \left[W(h_{0}) / W(0) \right]_{2}.$$
 (33)

Power flux lines **P** exit the cylinder surface at an sliding angle $\alpha = \arccos(h_0 / k_0)$ of inclination (i.e. $\cos(\mathbf{h}_0 \mathbf{P}) = h_0 / k_0$, $0 \le \alpha \le \pi / 2$, see Fig. 4-c) and become straight radial in the far zone at the distance $>> R^2 h_0$. In book [4], for example, the author could get the resonance dependence (Fig. 2-a) if he would normalized the ordinate by W(0), and the abscissa by k_0 and considered the *discrete* azimuthal frequencies $h_0 = n/R$ (n = 1,2,3,...) as interpolation nodes on the continuous axis of spatial frequencies. Note that the integral flow of the Poynting vector **P** through an arbitrary closed cylindrical surface \overline{S} (which embraces S) is equal to the integral power flow on the surface S of the cylindrical radiating pattern (Fig. 4-a).

6. Cylinder (axial phasor)

Now for the cylindrical wave equation (instead (29))

$$r^{-1} \left(r \psi_r' \right)_r' + \psi_{xx}'' = c^{-2} \psi_{tt}''$$
(34)

we consider the pattern (boundary condition)

where the phase runs along the axis of the cylinder S

(35)

 $-\left(\psi_r^{\prime}\right)_{\kappa=K} = U_0(\mathbf{r},t) = \exp(i\omega_0 t - ih_0 x) ,$

 $(-\infty < x < +\infty$, Fig. 5-a). So the normalized radiation resistance of such a pattern looks like

$$\left[\frac{W(h_0)}{W(0)}\right]_3 = \frac{\operatorname{Re}\left[i\left(\operatorname{H}_0^{(2)}(\xi)\right)\!\!\!/\left(\operatorname{H}_0^{(2)}(\xi)\right)\!\!\!/_{\xi}\right]_{\xi=k_0R}\sqrt{1-(h_0/k_0)^2}}{\operatorname{Re}\left[i\sqrt{1-(h_0/k_0)^2}\left(\operatorname{H}_0^{(2)}(\xi)\right)\!\!\!/\left(\operatorname{H}_0^{(2)}(\xi)\right)\!\!\!/_{\xi}\right]_{\xi=k_0R}}$$
(36)

(Fig. 5-b). Note that here the argument ξ of the Hankel function $H_0^{(2)}(\xi)$, when passing from $|h_0| < k_0$ to $|h_0| > k_0$, turns from purely real to purely imaginary. The quantity $[W(h_0)/W(0)]_3$ is closing to $[W(h_0)/W(0)]_1$ faster than $[W(h_0)/W(0)]_2$ (see the function

$$M_{3}(k_{0}R) = \max_{h_{0}} \left[W(h_{0}) / W(0) \right]_{3} , \qquad (37)$$

varying h_0 , in Fig. 5-c). Power flux lines **P** exit the cylinder surface in a taper angle $\alpha = \arccos(h_0 / k_0)$ (i.e. $\cos(\mathbf{h}_0 \mathbf{P}) = h_0 / k_0$, $0 \le \alpha \le \pi / 2$).



Figure 5. The phase runs along the axis "*x*" of cylinder S : (a) geometry of the boundary value problem; (b) normalized radiation resistance $\left[W(h_0) / W(0)\right]_3$ at different wave sizes $k_0 R$ of the cylinder cross-section, (the gray line shows the function $\left[W(h_0) / W(0)\right]_1$); (c)

dependence of the peak value M_3 on $k_0 R$.

7. Linear Chain of Acoustic Monopoles

Let us also consider the opposite example (with setting the speed, but without resonance) - a ruler (length $2L_0$) 2N+1 equidistantly (with a period $\ell = L_0 / N$, $k_0 \ell << 1$, N = 1,2,3,...) of distributed pulsating spheres



(acoustic monopoles) with radii $a \ll \ell$ (Fig. 6-a). Here, as in the previous sections, we set the normal vibrational velocity, but already on the surface of discrete pulsating spheres. The sinusoidal (with frequency ω_0) pulsations of the spheres are given the same amplitudes, and the phases of the pulsations are set linearly according to the law $\exp(-ih_0\ell n)$, where n is the sphere number $(-N \le n \le +N)$, $h_0 = |\mathbf{h}_0|$ is the phasor module \mathbf{h}_0 . Thus this is a wellknown 3D travelling wave antenna [9]. Then, for the normalized radiation resistance of the pattern (chain of monopoles), we obtain the expression

$$\left[\frac{W(h_0)}{W(0)}\right]_4 = \frac{\int_0^{\pi} \sin(\vartheta) B^2(\mathbf{N}, \ell, k_0, h_0, \vartheta) d\vartheta}{\int_0^{\pi} \sin(\vartheta) B^2(\mathbf{N}, \ell, k_0, 0, \vartheta) d\vartheta} , \qquad (38)$$

where

$$B(\mathbf{N}, \ell, k_0, h_0, \vartheta) = \frac{\sin[(2\,\mathbf{N}+1)(k_0\,\cos(\vartheta) - h_0)\ell/2]}{\sin[(k_0\,\cos(\vartheta) - h_0)\ell/2]}.$$
 (39)

The function $[W(h_0)/W(0)]_4$ graph (Fig. 6-b) has no resonance, and



Figure 6. Linear chain of acoustic monopoles: (a) geometry of the boundary value problem; (b) normalized radiation resistance of the chain of monopoles at different wave sizes L_0k_0 at $k_0a << k_0\ell << 1$.

The difference between the boundary value problem and the previous ones lies in the absence of diffraction (small scattering on rigid fixed spheres) of the fields of pulsating spheres on each other due to their small wave sizes ($ka \ll 1$) and relatively large distances ($\ell \gg a$) between their centers. Surface S becomes lumped into a set of 2 N+1 small spheres (see Fig. 6-a). In other words, we summarize in the far zone the fields of the single pulsating spheres that each of them creates in a space free from other spheres. In the same way, there is no resonance when noninteracting spheres are placed on a ring (if we try to formulate the problem in Section 5 in a similar way). For ($ka \ll 1$) $(\ell \gg a)$ it is indifferent (for $[W(h_0)/W(0)]_4$)

to make given velocity or pressure on the spheres. This is probably the reason for the absence of resonance. The maximum radiation power of the line of monopoles corresponds to the direction of the Poynting vector **P** in a cone with an inclination angle $\alpha = \arccos(h_0 / k_0)$ (i.e. $\cos(\mathbf{h}_0 \mathbf{P}) = h_0 / k_0$, $0 \le \alpha \le \pi / 2$). The radiation pressure is present as in above sections.

8. Spatially Localized Pattern on a Plane. For a rough estimate of the effect of amplification of acoustic radiation using a phasor \mathbf{h}_0 (at $|h_0| \rightarrow k_0$) at constant module of normal velocity amplitudes, we now consider (for the subsequent spectral representation) a pattern $U_0(\mathbf{r}, t) = U_0(x, y, t)$ localized on the plane z = 0 ($-\infty < x, y < \infty$) in the following form:

$$U_0(x, y, t) = [\operatorname{sinc}(\pi x / L_0) \operatorname{sinc}(\pi y / L_0)] \exp(i\omega_0 t - ih_0 x), \quad (41)$$

where $\operatorname{sinc}(\xi) = \frac{\sin(\xi)}{\xi}$, L_0 -space scale of localization. We need to estimate the ratio of the total power emitted by the pattern (41) at $h_0 = 0$ (Fig. 7–a) and the total power emitted by the pattern (41) at $h_0 \neq 0$ (Fig. 7–b). Below we will consider the boundary-value problem of radiation as a low-frequency filter of spatial frequencies with a transmission coefficient (13) (in terms of power (Fig. 7-c)

$$\left[W(h)/W(0)\right]_{I} = \mathbf{I}[k_{0} - h] / \sqrt{1 - (h/k_{0})^{2}}, \qquad (42)$$

where $I[\xi]$ -Heaviside step function (see (8)),

$$h = \pm \left| \mathbf{h} \right| = \pm \sqrt{h_x^2 + h_y^2} , \qquad (43)$$

 $h_{\mathbf{x}}$, $h_{\mathbf{y}}$ are the components of the vector \mathbf{h} ($\mathbf{h} \parallel (z = 0)$) of the spatial frequency along the axes "*x*" and "*y*", respectively (Fig. 7-d). Let's write the spatial Fourier spectrum of pattern (41) as

$$\widetilde{\widetilde{U}}(h_x, h_y; h_0) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} U_0(x, y, t) \exp[ih_x x + ih_y y] dx dy.$$
(44)

Using the property

$$\int_{-\infty}^{+\infty} \left[\sin(\pi x / L_0) / (\pi x / L_0) \right] \exp(-ihx) dx = L_0 \mathbf{I} \left[(\pi / L_0) - \left| h \right| \right]$$
(45)

of the function $\sin(\xi)/\xi$, we obtain Fourier spectrum

$$\widetilde{\widetilde{U}}(h_x, h_y; h_0) = L_0^2 \mathbf{I} \Big[(\pi / L_0) - \big| h_x - h_0 \big| \Big] \mathbf{I} \Big[(\pi / L_0) - \big| h_y \big| \Big] ,$$
(46)

and, accordingly, $\left[W(h_0)/W(0)\right]_5 = Q(h_0)/Q(0)$, where

$$Q(h_0) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \left[W(\sqrt{h_x^2 + h_y^2}) / W(0) \right]_1 \left| \tilde{U}_0(h_x, h_y; h_0) \right|^2 dh_x dh_y.$$
(47)

$$\lim_{L_0 k_0 \to \infty} \left[W(h_0) / W(0) \right]_4 = \mathbf{I} [k_0 - |h_0|].$$
(40)

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Fig. 7-e presents graphs of the magnitude $[W(h_0)/W(0)]_5$ for three wave sizes $2k_0L_0$ of the pattern (41) and the dependence of the maximum (at varying h_0) value (as peak)

$$M_{5}(2L_{0}k_{0}) = \max_{h_{0}} \left[W(h_{0}) / W(0) \right]_{5}$$
(48)

on wave size $2k_0L_0$ (or area of spatial localization) of the pattern (41). It is not hard to see that for $|k_0 - |h_0|| / k_0 \rightarrow 0$ (i.e. $|h_0|$ is closing to k_0) we obtain the value

$$\left[W(h_0 \approx k_0 - L_0^{-1}) / W(0)\right]_5 \approx \sqrt{k_0 L_0} >> 1.$$
(49)



Figure 7. On the spatially localized pattern (41) on the infinite plane: (a) " x" $h_0 = 0$; (b) " x" $h_0 \rightarrow k_0$; (c) one dimensional section $\begin{bmatrix} W(h) / W(0) \end{bmatrix}_1$ of low pass filter of boundary problem for pattern (41); (d) two dimensional (h_x , h_y , $h = \sqrt{h_x^2 + h_y^2}$) view on the low pass filter characteristics (black area means the no radiation) of boundary problem for pattern (41); (e) normalized radiation resistance $\begin{bmatrix} W(h) / W(0) \end{bmatrix}_5$ of pattern (41) at different wave sizes $2k_0L_0$, and value M_5 of its peak as function of wave dimension $2L_0k_0$ of (41).

It can be seen from (49) that the larger the wave dimensions k_0L_0 of the pattern (41), the more effectively and resonantly the pattern with a running phase (at

 $|k_0 - |h|| / k_0 \ll 1$) radiates than the in-phase pattern (at h = 0) at a given fixed module $|U_0(0,0,0)|$ of pattern amplitude.

Note that for finite wave sizes of the radiating pattern (sections 5-8, in contrast to sections 2-4), the real part $W(h_0)$ of field power flux on the surface of the pattern and the imaginary part $\overline{W}(h_0)$ are nonzero at all spatial frequencies h_0 .

9. Conclusion

In this work, the phenomenon of resonant sound emission by a boundary is analyzed analytically when a pattern is set on it in the form of a running sinusoidal spatial distribution of normal vibrational velocities at a certain temporal frequency (Section 1).

The initial problem is the resonant emission of sound by a spatially infinite harmonic distribution of normal velocities on an infinite plane (Section 2).

It is shown that setting a sinusoidal distribution of acoustic pressure on the plane does not generate resonant radiation (Section 2). In addition, it is shown that a linear chain of monopoles with a running phase of vibrational velocity amplitudes does not generate a radiation resonance (Section 7).

Further, the effect of the following factors on the magnitude of the resonant peak is estimated: surface curvature along the phasor (Section 5); surface curvature transversal to the phasor (Section 6); limitedness of the pattern in space (localization, Section 8).

A complete analogy of the phenomenon of resonant radiation in two problems is pointed out: (a) in the acoustic problem of Section 2; in the problem of electromagnetic radiation of a flat boundary, on which a traveling distribution of a tangential electric field with a polarization parallel to the phasor is specified (Section 3).

In practice, if we need to obtain the highest radiation power of a certain pattern with a limited dynamic range of actuators, then it would be most expedient to excite a sliding (with respect to the pattern) wave with a distribution of normal vibrational velocities with a traveling phase, and not excite a normal (with respect to the pattern) wave with an in-phase distribution normal vibrational velocities.

It has been shown that a resonantly radiating boundary with a traveling phase is capable of generating a timeconstant tangential radiation reaction force and,



consequently, can be used, for example, in designing an acoustic pump or for an active control of hydrodynamic boundary layer (Section 4).

Conflict of Interest

The author declares no conflict of interest.

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